

# Package ‘Rmalschains’

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**License** GPL-3

**Title** Continuous Optimization using Memetic Algorithms with Local Search Chains (MA-LS-Chains)

**LinkingTo** Rcpp

**Type** Package

**LazyLoad** yes

**Description** An implementation of an algorithm family for continuous optimization called memetic algorithms with local search chains (MA-LS-Chains), as proposed in Molina et al. (2010) <[doi:10.1162/evco.2010.18.1.18102](https://doi.org/10.1162/evco.2010.18.1.18102)> and Molina et al. (2011) <[doi:10.1007/s00500-010-0647-2](https://doi.org/10.1007/s00500-010-0647-2)>. Rmalschains is further discussed in Bergmeir et al. (2016) <[doi:10.18637/jss.v075.i04](https://doi.org/10.18637/jss.v075.i04)>. Memetic algorithms are hybridizations of genetic algorithms with local search methods. They are especially suited for continuous optimization.

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Rmalschains-package     *Getting started with the Rmalschains package*

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## Description

This package implements an algorithm family for continuous optimization called memetic algorithms with local search chains (MA-LS-Chains).

## Details

One of the main issues to optimize a real-coded function is the capability of the algorithm to realize a good exploration of the search space and, at the same time, to exploit the most promising region to obtain accurate solutions.

Memetic algorithms are hybridizations of genetic algorithms with local search methods. They are especially suited for continuous optimization, as they combine the power of evolutionary algorithms to explore the search space with a local search method to find the local optimum of a promising region. In these algorithms, it is recommended to increase the effort invested in the local search (measured in number of evaluations, called intensity) in the improvement of the most promising solution. However, it is not easy to decide the right intensity for each solution.

MA-LS-Chains is a steady-state memetic algorithm, which combines a steady-state genetic algorithm with various different local search methods. In contrast to the generational approach, where all individuals are substituted in an iteration, in the steady-state genetic algorithm in each iteration only one solution, the worst one, is substituted in the population. This makes it possible to not lose the improvement obtained by the local search over the individuals.

For MA-LS-Chains, the current state of the local search algorithm is stored along with the individuals. So, it becomes possible to run the local search a fixed number of iterations, stop it, and possibly later continue the previous local search over the same individual. In this way, MA-LS-Chains controls the application of the local search to the most promising solutions.

The package implements various different local search strategies:

- CMA-ES The Covariance Matrix Adaptation Evolution Strategy

- SW A Solis Wets solver
- SSW Subgrouping Solis Wets
- Simplex

CMA-ES is a very effective local search strategy, but quite complicated, and it does not scale well if the amount of parameters to optimize is huge. The Solis Wets solver is pretty simple and therewith fast. The SSW strategy is an adapted version of the Solis Wets solver for high dimensional data, so that the algorithm with this type of local search scales well with the dimensionality of the data. It applies the Solis Wets solver to randomly chosen subgroups of variables (Subgrouping Solis Wets).

All the local search methods can also be used directly, without making use of the evolutionary algorithm.

The package contains some demos illustrating its use. To get a list of them, type:

```
library(Rmalschains)
demo()
```

The demos currently available are `claw`, `rastrigin`, `sphere`, `rastrigin_highDim`, and `rastrigin_inline`. So in order to, e.g., execute the `claw` demo, type

```
demo(claw)
```

All algorithms are implemented in C++, and they run pretty fast. A usual processing to speed up optimization is to implement the objective function also in C/C++. However, a bottleneck in this approach is that the function needs to be passed as an R function, so that the optimizer needs to go back from C++ to R to C/C++ in each call of the target function. The package provides an interface which allows to pass the C/C++ target function directly as a pointer. See the `rastrigin_inline` demo for how to do that. The demo also shows how an environment can in this approach be used to pass additional parameters to the target function.

For theoretical background of the algorithm, the reader may refer to the cited literature, where the algorithms were originally proposed.

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## References

Bergmeir, C., Molina, D., Benítez, J.M. Memetic Algorithms with Local Search Chains in R: The Rmalschains Package (2016) *Journal of Statistical Software*, 75(4), 1-33., doi:10.18637/jss.v075.i04

Molina, D., Lozano, M., Sánchez, A.M., Herrera, F. Memetic algorithms based on local search chains for large scale continuous optimisation problems: MA-SSW-Chains (2011) *Soft Computing*, 15 (11), pp. 2201-2220.

Molina, D., Lozano, M., Herrera, F. MA-SW-Chains: Memetic algorithm based on local search chains for large scale continuous global optimization (2010) 2010 IEEE World Congress on Computational Intelligence, WCCI 2010 - 2010 IEEE Congress on Evolutionary Computation, CEC 2010.

Molina, D., Lozano, M., García-Martínez, C., Herrera, F. Memetic algorithms for continuous optimisation based on local search chains (2010) Evolutionary Computation, 18 (1), pp. 27-63.

## See Also

`malschains`, `malschains.control`

## Examples

```
#####
#Example for maximization of the claw function
#####

claw <- function(xx) {
  x <- xx[1]
  y <- (0.46 * (dnorm(x, -1, 2/3) + dnorm(x, 1, 2/3)) +
         (1/300) * (dnorm(x, -0.5, 0.01) + dnorm(x, -1,
                                                     0.01) + dnorm(x, -1.5, 0.01)) + (7/300) *
         (dnorm(x, 0.5, 0.07) + dnorm(x, 1, 0.07) + dnorm(x,
                                                     1.5, 0.07)))
  return(y)
}

#use MA-CMA-Chains
res.claw <- malschains(function(x) {-claw(x)}, lower=c(-3), upper=c(3),
                       maxEvals=50000, control=malschains.control(popsize=50,
                                                     istrp=300, ls="cmaes", optimum=-5))

#use only the CMA-ES local search
res.claw2 <- malschains(function(x) {-claw(x)}, lower=c(-3), upper=c(3), verbosity=0,
                        maxEvals=50000, control=malschains.control(ls="cmaes",
                                                      lsOnly=TRUE, optimum=-5))

#use only the Simplex local search
res.claw3 <- malschains(function(x) {-claw(x)}, lower=c(-3), upper=c(3), verbosity=0,
                        maxEvals=50000, control=malschains.control(ls="simplex",
                                                      lsOnly=TRUE, optimum=-5))

x <- seq(-3, 3, length=1000)
claw_x <- NULL
for (i in 1:length(x)) claw_x[i] <- claw(x[i])

plot(x,claw_x, type="l")
points(res.claw$sol, -res.claw$fitness, col="red")
points(res.claw2$sol, pch=3, -res.claw2$fitness, col="blue")
points(res.claw3$sol, pch=3, -res.claw3$fitness, col="green")

#####
#Example for the rastrigin function
#####
```

```

rastrigin <- function(x) {

  dimension <- length(x)

  res <- 0.0
  for (i in 1:dimension) {
    res <- res + (x[i]*x[i] - 10.0*cos(2.0*pi*x[i]) + 10.0)
  }

  res
}

res.rastrigin1 <- malschains(rastrigin, lower=seq(-1.0, -1.0, length=30),
                               upper=seq(1.0, 1.0, length=30), maxEvals=50000,
                               control=malschains.control(efort=0.8, alpha=0.3,
                               popsize=20, istep=100, ls="simplex"))

res.rastrigin2 <- malschains(rastrigin, lower=seq(-1.0, -1.0, length=30),
                               upper=seq(1.0, 1.0, length=30), maxEvals=50000,
                               initialpop = seq(0.1, 0.1, length=30),
                               control=malschains.control(popsize=50,
                               istep=300, ls="cmaes"))

res.rastrigin1
res.rastrigin2

```

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malschains*Perform optimization with the MA-LS-Chains algorithm*

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## Description

This is the main function of the package. It minimizes the output of the function fn (for maximization, change the sign of the output of fn).

## Usage

```

malschains(
  fn,
  lower,
  upper,
  dim,
  maxEvals = 10 * control$istep,
  verbosity = 2,
  initialpop = NULL,
  control = malschains.control(),
  seed = NULL,
  env
)

```

## Arguments

|            |  |
|------------|--|
| fn         | The function to minimize.  |
| lower      | The lower bound (or bounds) of the search domain.  |
| upper      | The upper bound (or bounds) of the search domain.  |
| dim        | The dimension of the problem (if lower and upper are vectors it is not needed).  |
| maxEvals   | The maximal number of evaluations of the fitness function.   |
| verbosity  | Set the verbosity level. Currently, meaningful values are 0, 1, 2  |
| initialpop | An initial population for the evolutionary algorithm can be submitted (as a matrix). Here, prior knowledge can be introduced to get better results from the algorithm. |
| control    | A list containing the main options of the algorithm. See <a href="#">malschains.control</a> .  |
| seed       | A seed value for the random number generator.  |
| env        | The environment in which to evaluate the fitness function. If not given, it is generated.  |

## Details

The output of the function when run with `verbosity=2` is the following:

- `EA::PopFitness` The fitness of the best, the one at the 1st quartile, the one at the 3rd quartile, and the worst individual.
- `EA::Improvement` Improvement of the individuals at the according ranked positions in the population (best, 1st quartile, 3rd quartile, worst).
- `LS` The number of the individual which is improved on (in braces), its fitness before and after application of the LS procedure, and their difference.
- `EABest` If the best fitness present in the population changed: same as `LS`.

## Value

the function returns a list containing the best individual, `sol`, and its `fitness`. Furthermore, it contains some information on the optimization process, which can be seen using [print.malschains](#).

## References

Molina, D., Lozano, M., Sánchez, A.M., Herrera, F. Memetic algorithms based on local search chains for large scale continuous optimisation problems: MA-SSW-Chains (2011) *Soft Computing*, 15 (11), pp. 2201-2220.

Molina, D., Lozano, M., García-Martínez, C., Herrera, F. Memetic algorithms for continuous optimisation based on local search chains (2010) *Evolutionary Computation*, 18 (1), pp. 27-63.

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|                                 |  |
|---------------------------------|--|
| <code>malschains.control</code> | <i>Sets and initializes the main parameters of the algorithm</i> |
|---------------------------------|--|

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## Description

This is a function that initializes and sets the parameters of the algorithm. It generates a list of parameters, to be used with the `malschains` function.

## Usage

```
malschains.control(
  popsize = 50,
  ls = "cmaes",
  istep = 500,
  effort = 0.5,
  alpha = 0.5,
  optimum = -Inf,
  threshold = 1e-08,
  lsOnly = FALSE,
  lsParam1 = 0,
  lsParam2 = 0
)
```

## Arguments

|                      |   |
|----------------------|---|
| <code>popsize</code> | The population size of the evolutionary algorithm.  |
| <code>ls</code>      | The local search method. Currently implemented are <code>cmaes</code> , <code>sw</code> , <code>simplex</code> , and <code>ssw</code> . Usually, the <code>cmaes</code> local search strategy will give good results. However, it does not scale well with the problem size. So, if performance is needed, the <code>sw</code> strategy is a better choice. If the problem is high-dimensional, the <code>ssw</code> strategy is promising, which selects randomly 20% of the variables for optimization. |
| <code>istep</code>   | The number of iterations of the local search. I.e., if the local search is started or re-started on an individual, it will be executed for an <code>istep</code> number of iterations. This parameter depends on the local search used. For <code>cmaes</code> , usually an <code>istep</code> of 300 is a good choice. For the other local search methods, an <code>istep</code> of 100 performs better.   |
| <code>effort</code>  | A value between 0 and 1 which gives the ratio between the amount of evaluations that are used for the local search and for the evolutionary algorithm, respectively. A higher effort means more evaluations for the evolutionary algorithm. So, if exploration of the search space is more important than finding local optima, <code>effort</code> is to be chosen higher.   |
| <code>alpha</code>   | The alpha parameter from crossover BLX-alpha. A lower value (< 0.3) reduces diversity, a higher value increases diversity.  |
| <code>optimum</code> | The optimum to achieve. The default is zero, as in many minimization problems a value of zero can be considered optimal.  |

|           |  |
|-----------|--|
| threshold | A threshold which defines for the local search how much improvement is considered as no improvement. If this value is chosen too low (zero), then the local search will usually always try to improve on the best individual, even if it is already located very close to a local optimum. |
| lsOnly    | Apply only the local search algorithm, and not MA-LS-Chains  |
| lsParam1  | First (optional) parameter. Currently, if local search is cmaes, this is the parameter popsize/lambda of cmaes. If it is not set or not positive, cmaes will calculate this automatically using a heuristic.   |
| lsParam2  | Second (optional) parameter. Currently, if local search is cmaes, this is the parameter parentssize/mu of cmaes. If it is not set, not positive, or not smaller lambda, cmaes will calculate this automatically using a heuristic.   |

**Value**

returns a list with the parameter names and values of the supplied parameters.

**References**

Molina, D., Lozano, M., Sánchez, A.M., Herrera, F. Memetic algorithms based on local search chains for large scale continuous optimisation problems: MA-SSW-Chains (2011) Soft Computing, 15 (11), pp. 2201-2220.

Molina, D., Lozano, M., García-Martínez, C., Herrera, F. Memetic algorithms for continuous optimisation based on local search chains (2010) Evolutionary Computation, 18 (1), pp. 27-63.

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|                         |  |
|-------------------------|--|
| <b>print.malschains</b> | <i>Generic print function for malschains results</i> |
|-------------------------|--|

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**Description**

Print out some characteristics of a **malschains** result. The result shows besides the best solution and its fitness the total number of evaluations spent for both EA and LS, the ratio of the spent evaluations (also called effort), the ratio of total improvement of the fitness, the percentage of times that application of the EA/LS yielded improvement, and some timing results in milliseconds.

**Usage**

```
## S3 method for class 'malschains'
print(x, ...)
```

**Arguments**

|     |   |
|-----|---|
| x   | the <b>malschains</b> result                        |
| ... | additional function parameters (currently not used) |

**Value**

the original supplied **malschains** object is returned, as **invisible()**.

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